ICCS: The what, why, and how.

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Institute of Computing for Climate Science

SCHMIDT FUTURES







1850-2021 (Ed Hawkins "Warming stripes")



Increasing resolution



graphics from 4th IPCC report (2007)





Increasing process complexity







Low resolution 300km Mid 25-100km (typical GCM) Higher resolution 1-5km



Collaboration Communication





Collaboration Communication



1. Scaling computational performance

42 Years of Microprocessor Trend Data



Original data up to the year 2010 collected and plotted by M. Horowitz, F. Labonte, O. Shacham, K. Olukotun, L. Hammond, and C. Batten New plot and data collected for 2010-2017 by K. Rupp

Approximating sub grid processes



NASA / Wikimedia Commons

Uncertainty / error vs. expense

Hillman et al. 2020







Solution: Data-driven subgrid closures

CNN model

Train on real data or high-resolution model



Explainability?

Integration into GCM?



2. Scaling collaborations

The Two Complexities

Inherent



Accidental



Solution: Software engineering tools & techniques

Processes AGILE **SPRINT 2 SPRINT**

Version control



Debugging

Profiling

& public curators

Build systems & containers

GitHub GitLab



Testing and verification





Structural and culturual/sociological change



Software Sustainability Institute





Society of Research Software Engineers



3. Scaling communication

Environmental Data Science (2022), 1: e11, 1–28 doi:10.1017/eds.2022.10



APPLICATION PAPER 🚺 😳

A sensitivity analysis of a regression model of ocean temperature

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Abstract

There has been much recent interest in developing data-driven models for weather and climate predictions. However, there are open questions regarding their generalizability and robustness, highlighting a need to better understand how they make their predictions. In particular, it is important to understand whether data-driven models learn the underlying physics of the system against which they are trained, or simply identify statistical patterns without any clear link to the underlying physics. In this paper, we describe a sensitivity analysis of a regression-based model of ocean temperature, trained against simulations from a 3D ocean model setup in a very simple configuration. We show that the regressor heavily bases its forecasts on, and is dependent on, variables known to be key to the physics such as currents and density. By contrast, the regressor does not make heavy use of inputs such as location, which have limited direct physical impacts. The model requires nonlinear interactions between inputs in order to show any meaningful skill—in line with the highly nonlinear dynamics of the ocean. Further analysis interprets the ways certain variables are used by the regression model. We see that information about the vertical profile of the water column reduces errors in regions of convective activity, and information about the currents reduces errors in regions dominated by advective processes. Our results demonstrate that even a simple regression model is capable of learning much of the physics of the system being modeled. We expect that a similar sensitivity analysis could be usefully applied to more complex ocean configurations.

Impact Statement

Machine learning provides a promising tool for weather and climate forecasting. However, for data-driven forecast models to eventually be used in operational settings we need to not just be assured of their ability to perform well, but also to understand the ways in which these models are working, to build trust in these systems. We use a variety of model interpretation techniques to investigate how a simple regression model makes its predictions. We find that the model studied here, behaves in agreement with the known physics of the system. This works shows that data-driven models are capable of learning meaningful physics-based

```
module simulation_mod
 1
      use helpers mod
 2
       implicit none
 3
 4
      contains
 5
 6
       subroutine compute_tentative_velocity(u, v, f, g, flag, del_t)
 8
        real u(0:imax+1, 0:jmax+1), v(0:imax+1, 0:jmax+1), f(0:imax+1, 0:jmax+1), &
 9
             g(0:imax+1, 0:jmax+1)
10
        integer flag(0:imax+1, 0:jmax+1)
11
        real, intent(in) :: del_t
12
13
         integer i, j
14
         real du2dx, duvdy, duvdx, dv2dy, laplu, laplv
15
16
        do i = 1, (imax-1)
17
          do j = 1, jmax
18
            ! only if both adjacent cells are fluid cells */
19
            if (toLogical(iand(flag(i,j), C_F)) .and.
                                                                                   &
20
                 toLogical(iand(flag(i+1,j), C_F))) then
21
22
               du2dx = ((u(i,j)+u(i+1,j))*(u(i,j)+u(i+1,j))+
                                                                                   &
23
                      gamma*abs(u(i,j)+u(i+1,j))*(u(i,j)-u(i+1,j))-
                                                                                   &
24
                      (u(i-1,j)+u(i,j))*(u(i-1,j)+u(i,j))-
                                                                                   &
25
                      gamma * abs(u(i-1,j)+u(i,j))*(u(i-1,j)-u(i,j)))
                                                                                   &
26
                      /(4.0*delx)
27
               duvdy = ((v(i,j)+v(i+1,j))*(u(i,j)+u(i,j+1))+
                                                                                   &
28
                      gamma*abs(v(i,j)+v(i+1,j))*(u(i,j)-u(i,j+1))-
                                                                                   &
29
                      (v(i,j-1)+v(i+1,j-1))*(u(i,j-1)+u(i,j))-
                                                                                   &
30
                      gamma*abs(v(i,j-1)+v(i+1,j-1))*(u(i,j-1)-u(i,j)))
                                                                                   &
31
                            /(4.0*dely)
32
               laplu = (u(i+1,j)-2.0*u(i,j)+u(i-1,j))/delx/delx+
                                                                                   &
33
                      (u(i,j+1)-2.0*u(i,j)+u(i,j-1))/dely/dely
34
              f(i,j) = u(i,j) + del_t*(laplu/Re-du2dx-duvdy)
35
36
            else
37
              f(i,j) = u(i,j)
38
             end if
39
          end do
40
         end do
41
```

3. Challenge: conflation of concerns in code

Solution strategy Prediction calculation Abstract model









Padstriact stredetytion

programs





3. Challenge: conflation of concerns in code

papers

- Extra technical documentation
- Clear systems design
- High modularity



But language support possible: more research needed

Is a future language tailored to science possible?





Collaboration Communication







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Artificial Intelligence

Data Science



Mathematics Software Engineering

Computer Science Programming Langauges



https://www.schmidtfutures.com/our-work/virtual-earth-system-research-institute-vesri/

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Our Work Virtual Earth ... Home

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Our Work











DataWave

SASIP



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Laura Cimoli



Kacper Kornet







2x more hiring

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Simon Clifford

Ben Orchard



Jack Atkinson



Jim Denhom

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More on the way...









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